



SCOPE: An Open and Softwarized Prototyping Platform for NextG Systems

Leonardo Bonati

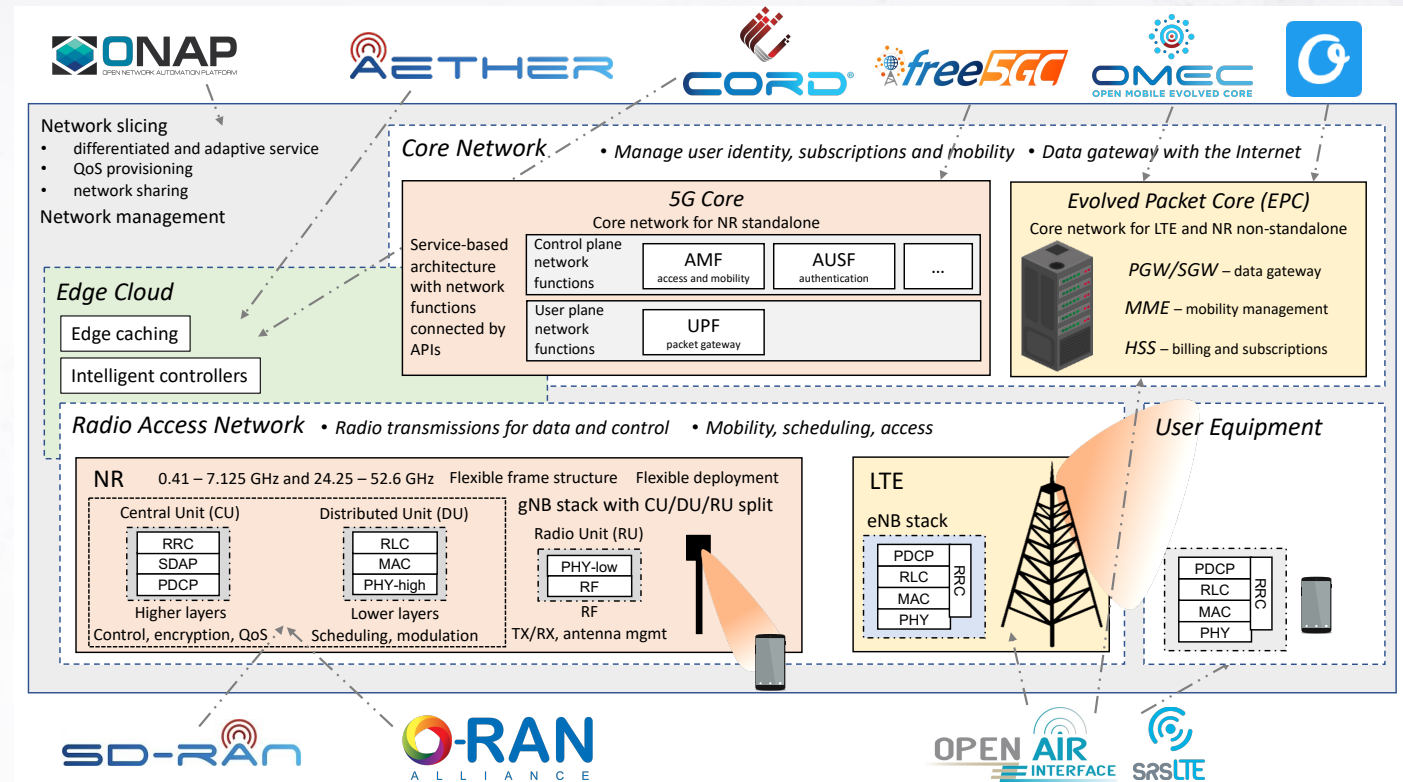
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L. Bonati, S. D'Oro, S. Basagni, and T. Melodia, "*SCOPE: An Open and Softwarized Prototyping Platform for NextG Systems*," in Proceedings of ACM MobiSys, June 2021

Repository: <https://github.com/wineslab/colosseum-scope>

Key Role of Softwarization and Virtualization in NextG Networks

- **Deploy** custom services on generic hardware
- **Program** network functionalities in **software**
- **Dynamically optimize** network performance



L. Bonati, M. Polese, S. D'Oro, S. Basagni, and T. Melodia, "Open, Programmable, and Virtualized 5G Networks: State-of-the-Art and the Road Ahead," Computer Networks, vol. 182, December 2020

Need for:

- Open research tools to **prototype** NextG solutions in **controlled environments**
- **Large-scale datasets** to design/train AI/ML solutions

SCOPE: Toward Easier Reconfigurability

- Extends srsRAN with:
 - Network slicing functionalities
 - MAC-layer functionalities (e.g., custom scheduling policies)
 - PHY-layer functionalities (e.g., control of MCS)
- Automatic **data-collection** of RAN statistics
- Flexible **open APIs** to **control** the RAN in **real time**
- Portable implementation through LXC containers
- Enables to **prototype** custom control logic **at-scale**

Fully-integrated with Colosseum

Easier to run experiments*

- w/o SCOPE: Several hours to **setup** and **manually run** every single experiment
- w/ SCOPE: **Configure** container **once**, “seamlessly” **run different experiments** (at scale) from **single CLI**, easily modify configuration parameters/scenarios

Easier to collect data*

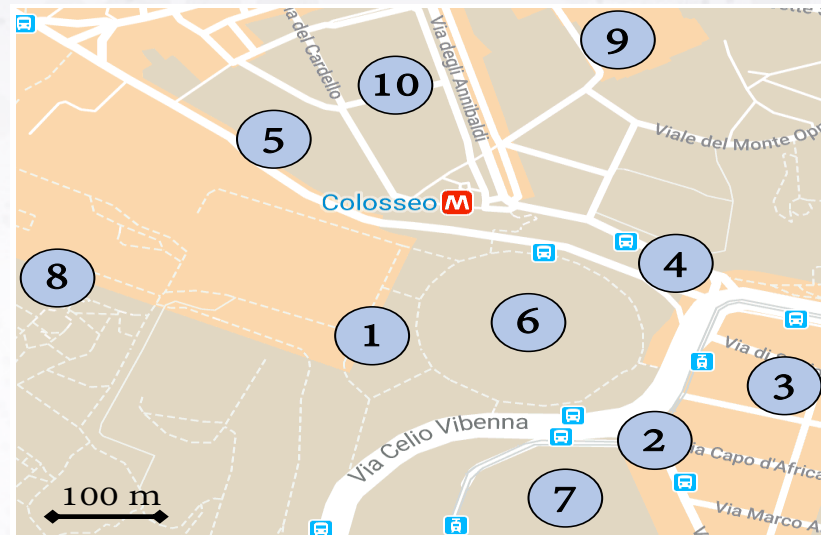
- w/o SCOPE: **manually** perform several hundreds of experiments and collect data → **may take a very long time**
- w/ SCOPE: **set up once** and **run multiple automatic jobs** on Colosseum in parallel, get data at the end → **easier and faster**

SCOPE & Colosseum Example

W/ Colosseum

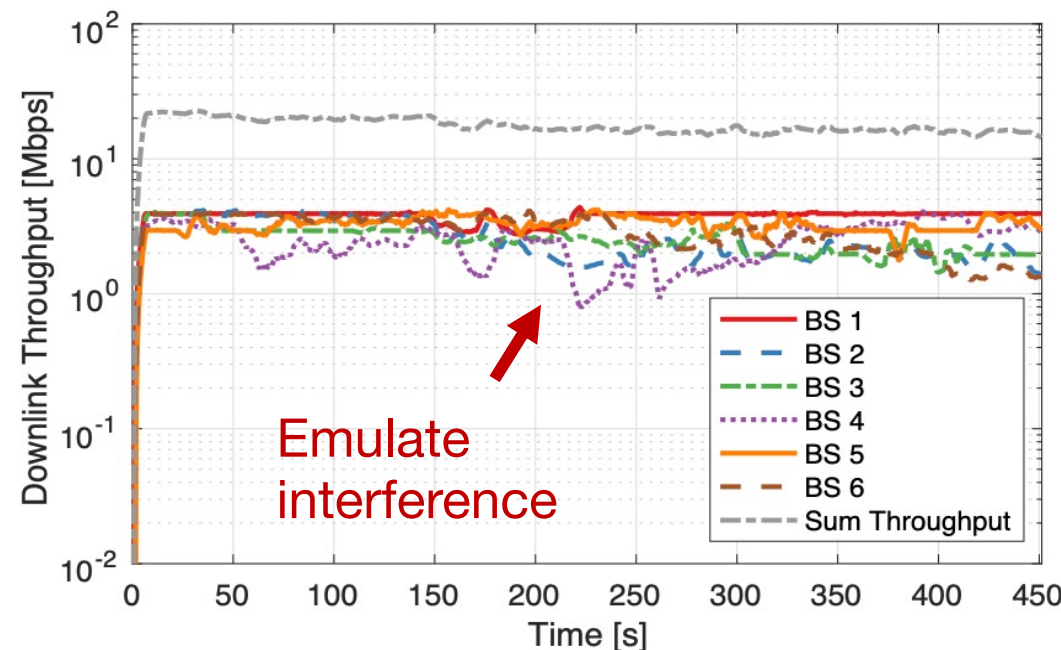
- Emulate Rome downtown scenario
- Deploy softwareized base stations & UEs
- Evaluate performance

Rome BS locations from
OpenCellid: <https://opencellid.org>



W/o Colosseum

- Go **on-site** with equipment
- **Outcome may vary** based on hour of the day, weather conditions, etc.



SCOPE Example

- Log into Colosseum website*

- Request a new reservation

- Specify name/date/time/duration

- Set number of nodes

- Select the **scope** container image for the nodes (default credentials: **root/scope**)

The screenshot shows the 'Request New Reservation' page in the Colosseum web interface. The navigation bar includes 'Home', 'Reservations', 'Batch Jobs', and 'Scenarios'. The 'Reservations' tab is active. The form contains the following fields:

- Name: colosseum-scope
- Start date: 2021/11/17
- Start time: 11:20 AM
- Duration: 60 minutes
- Number of SRNs: 4 (97 max available)
- Default image: scope
- Node 1: scope

A note states: "Note: 5 minutes of your reservation will be used for data transfer".

The reservation calendar shows availability for Quad 1 (25 available), Quad 2 (26 available), Quad 3 (29 available), and Quad 4 (17 available). The calendar grid shows a reservation for Wednesday, November 17, 2021, from 12:00 am to 8:00 pm. A vertical green bar highlights the reservation time slot.

SCOPE API at a High-level

Control RAN via **open APIs**:

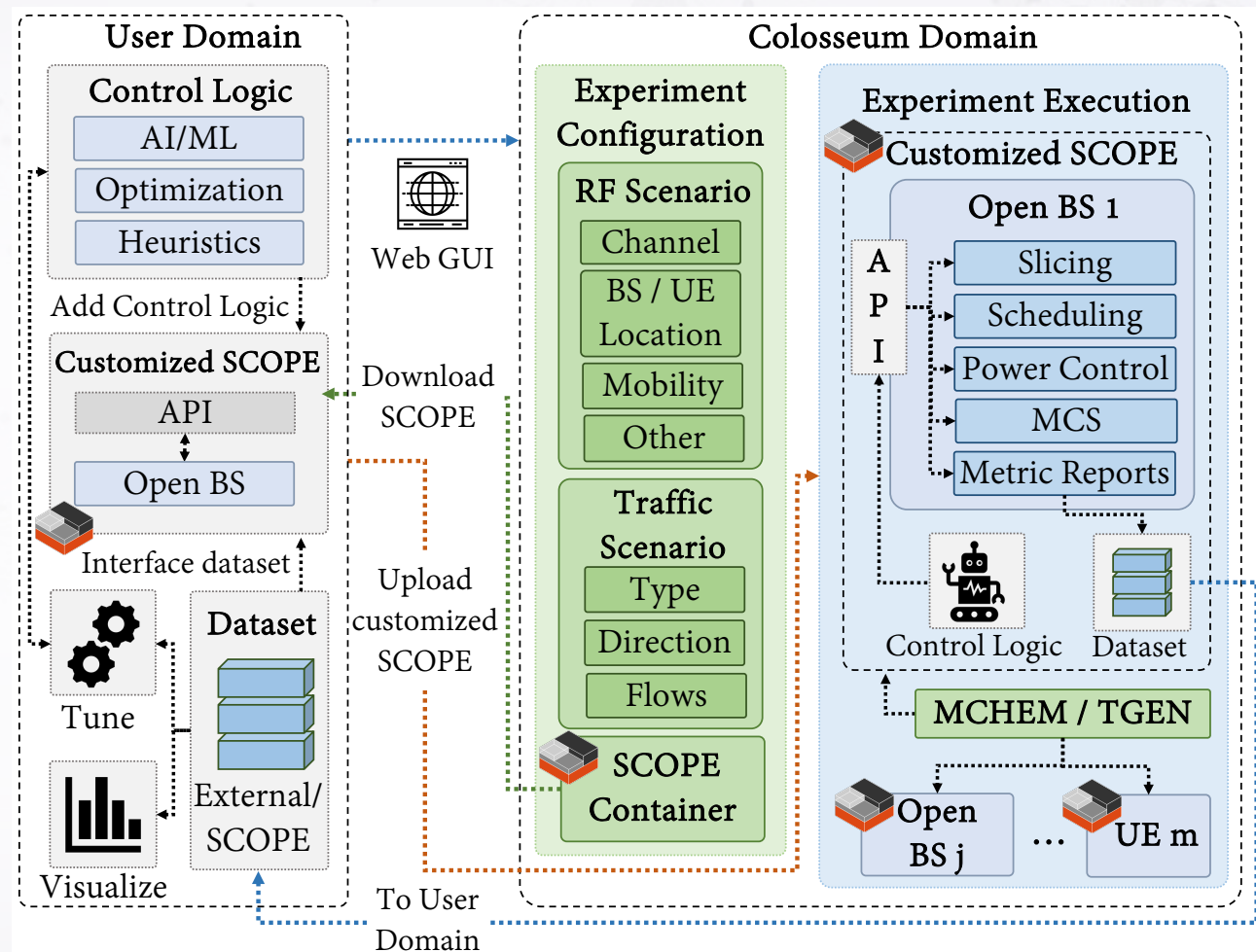
- Control **network slicing** (e.g., associate users to slices, set slicing policies and modify at run-time)
- Control **MAC-layer parameters** (e.g., change slicing policies at run-time)
- Control **PHY-layer parameters** (e.g., power control and adaptation, MCS selection at run-time)
- **Data collection** (e.g., collect and query performance metrics at run-time)

```
1. import scope_api as sc, time
2. while experiment_running:
3.     wnd_metrics = sc.read_metrics(time_window)
4.     for slice_id, slice_metrics in wnd_metrics.items():
5.         slice_users = slice_metrics['ue']
6.         slice_rbg = slice_metrics['rbg']
7.         sc.set_mcs(slice_users, mcs_level, 'dl')
8.         if slice_metrics['buffer'] > threshold:
9.             sc.set_slice(slice_id, 'proportionally', slice_rbg + 2)
10.        else:
11.            sc.set_slice(slice_id, 'round-robin', slice_rbg - 2)
12.    time.sleep(timeout)
```

High-level example of SCOPE APIs.

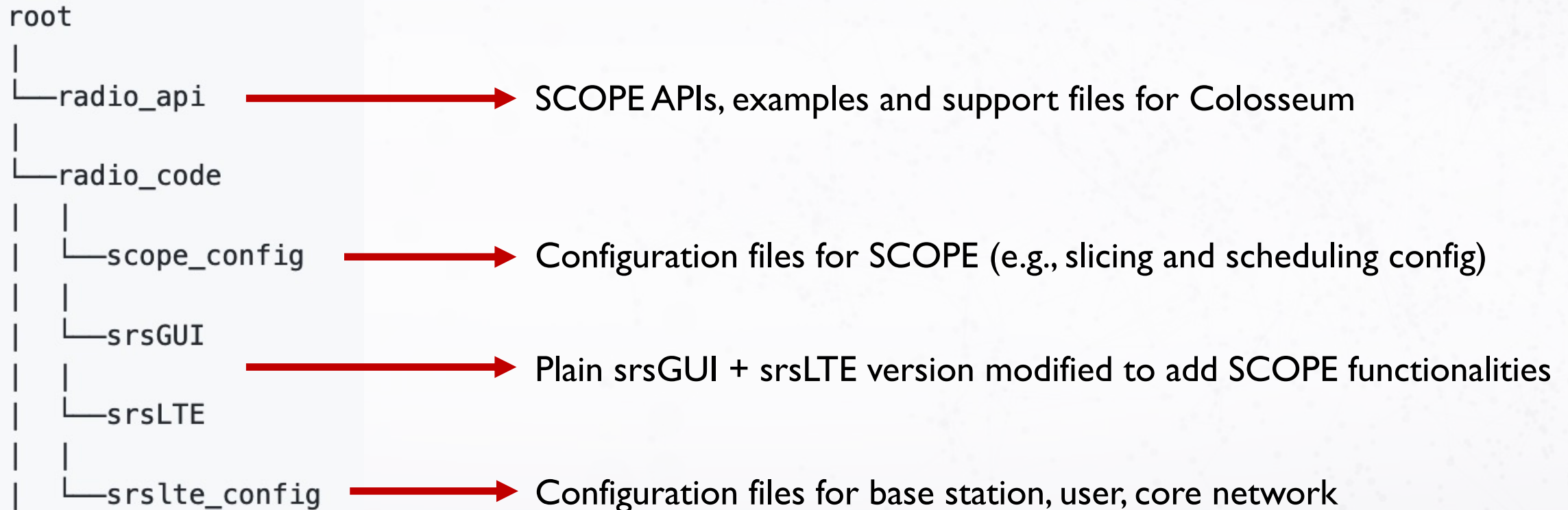
Prototyping At-Scale Example

- Extend the provided “plain” SCOPE container with **custom control logic**
- **Select** RF and traffic **scenarios** to run
- Interface with SCOPE APIs to **optimize** network performance **at run-time**
- Save metrics and statistics for **offline parsing/dataset creation**



SCOPE Quick Tour

SCOPE structure:



SCOPE Quick Tour: radio_api

Main SCOPE API scripts:

- **scope_start.py**: quick start script for running SCOPE on Colosseum testbed
 - **python3 scope_start.py --config-file radio_interactive.conf**
 - Parse configuration files
 - Configure/start cellular applications
 - Using the quick start script outside Colosseum might require minor adjustments
- **scope_api.py**: APIs to interact with/reconfigure the base station
- **constants.py**: constant parameters used by the other scripts
- **support_functions.py**: additional support functions

SCOPE Quick Tour: radio_api

Exemplary scripts (to be run at the base station):

- **heuristic.py**: read performance metrics from dataset and implement arbitrary heuristic policies, in this case:
 - read run-time performance metrics
 - modify slicing and scheduling policies based on metrics
- **slice_heuristic.py**: periodically modify number of PRBs allocated to the network slices

SCOPE Quick Tour: radio_api

Configuration files:

- **radio_interactive.conf**: exemplary configuration file to use with the **scope_start.py** script
- **radio.conf**: dummy configuration file replaced by Colosseum when running batch jobs
- **heuristic.conf**: exemplary configuration file to use with **heuristic.py** script
- **slice_heuristic.conf**: Exemplary configuration file to use with **slice_heuristic.py** script

+ Additional support files for Colosseum

Main API Configuration Parameters

General configuration:

- **capture-pkts**: enable packet capture/dumps on .pcap files
- **config-file**: JSON-formatted configuration file where to read these parameters from
- **iperf**: generate traffic through iPerf3

MAC- PHY-layer configuration:

- **global-scheduling-policy**: set MAC-layer scheduling policy for all slices (choose among round-robin, waterfilling and proportionally fair)
- **force-dl-modulation/force-ul-modulation**: Force downlink/uplink modulation of base station/users

Main API Config Parameters, cont'd

Network slicing:

- **custom-ue-slice**: use users-slice associations passed through the slice-users parameter
- **network-slicing**: enable network slicing
- **slice-allocation**: configure slicing policies
- **slice-scheduling-policy**: select scheduling policy for each slice of the network

SCOPE Quick Tour: `scope_config`

Configuration files periodically reloaded at run time by the “*Scopified*” srsRAN:

- **`scope_cfg.txt`**: global configuration file to enable/disable SCOPE functionalities
- **`config`**: directory populated at run time with user-related parameters
- **`metrics/csv`**: CSV files on user performance are automatically logged in this directory at run time

SCOPE Quick Tour: scope_config, cont'd

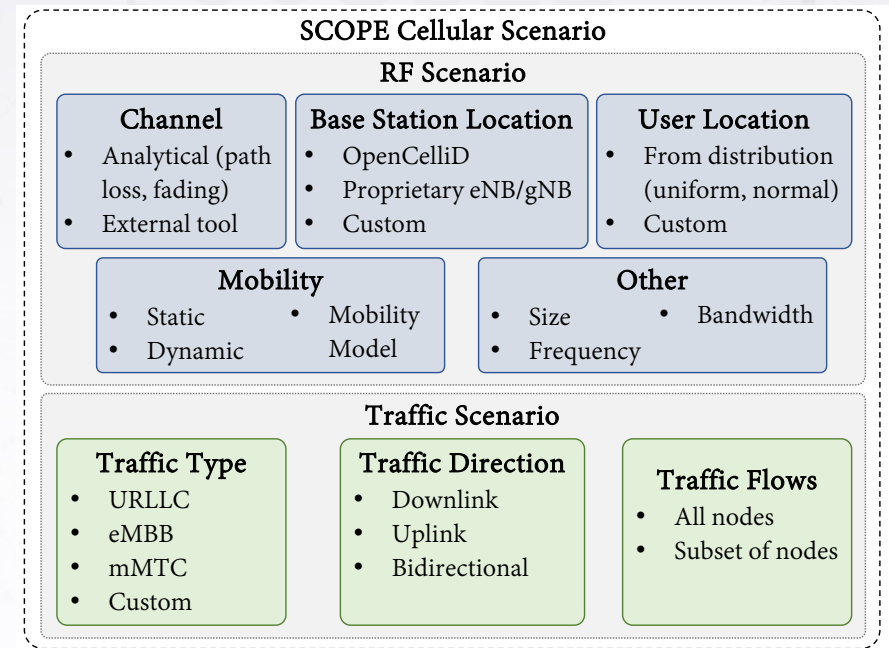
Configuration files:

- **slicing**: contains slicing- and user- related configuration files
 - **slice_allocation_mask_tenant_*.txt**: RBG allocation mask for tenant
 - **slice_scheduling_policy.txt**: specifies the scheduling policy to for each network slice
 - **ue_imsi_slice.txt**: slice-users associations
 - **ue_imsi_modulation_dl.txt/ue_imsi_modulation_ul.txt**: configuration file to force downlink/uplink modulation for specific users

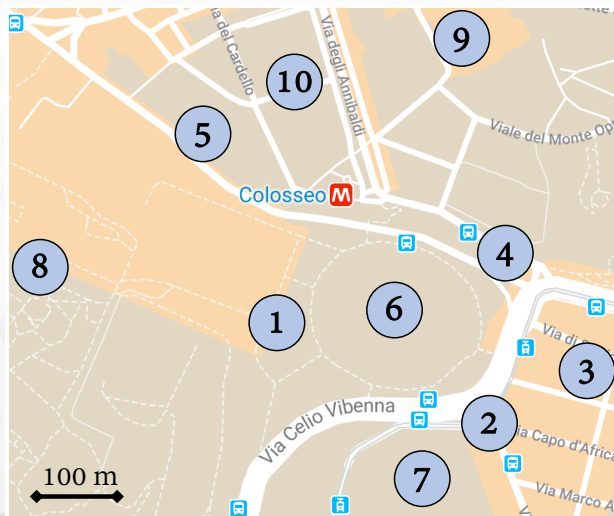
SCOPE Cellular Scenarios

Allows to specify:

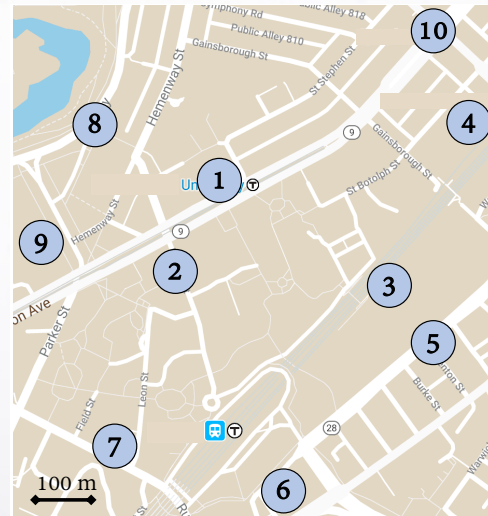
- **Wireless channel effects**, e.g., path loss, position/distance of BSs/UEs, mobility/speed, etc.
- **Traffic flows and types** among nodes



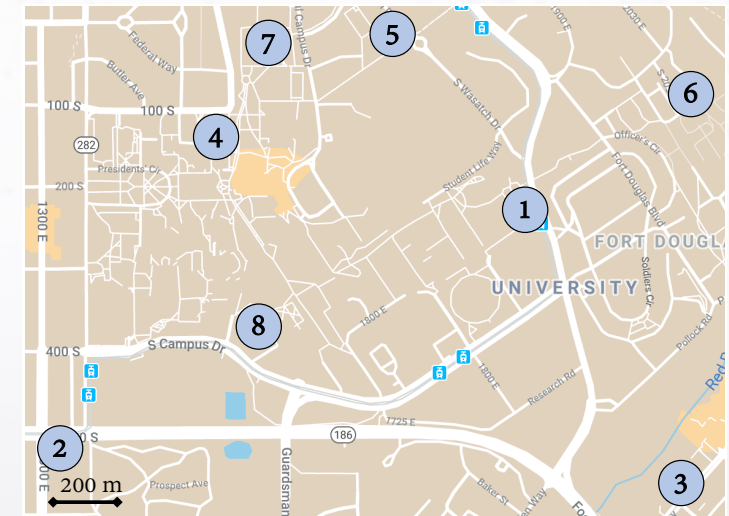
Example of designed large-scale scenarios (blue circles = BS):



Rome, Italy



Boston, MA

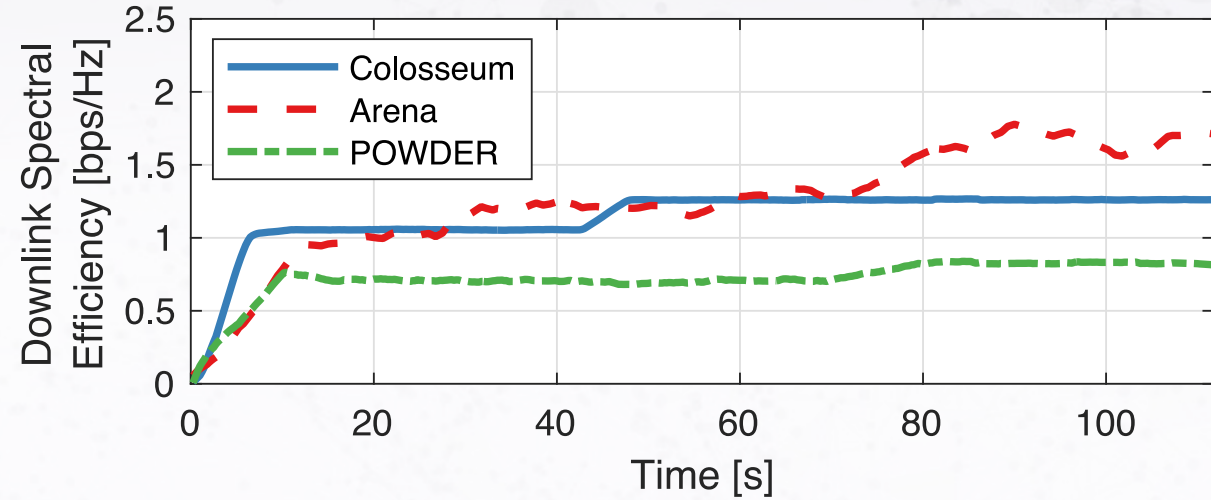


Salt Lake City, UT (POWDER)

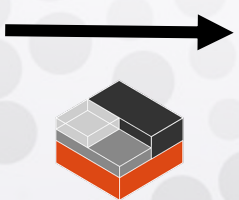
Prototype At-scale, Test in the Wild

SCOPE can be **ported to different testbeds**

- **Prototype** on Colosseum
- **Validate in real environment**
- **Test** large-scale capabilities on **city-scale platforms**

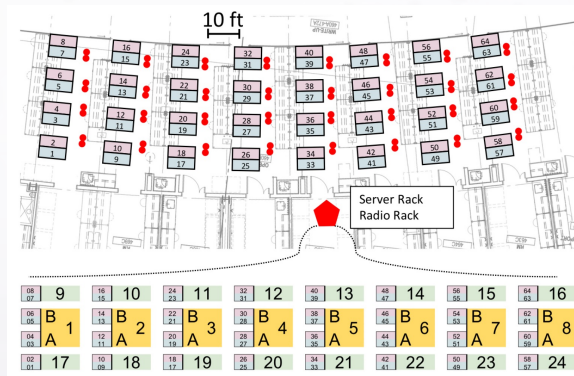
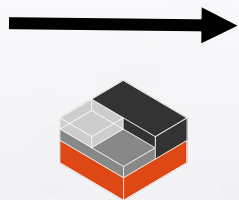


Test at-a-scale on emulated scenarios

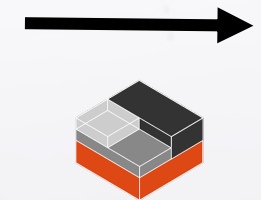


COLOSSEUM
at Northeastern University

Validate in real wireless environment



Test large-scale capabilities





Thank You!

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